

Mathematical Theories of Communication: Old and New

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Communication = What?

- Today: Digital Communication
 - i.e., Communicating bits/bytes/data ...
 - As opposed to "radio waves for sound"
- Challenge? Communication can be ...
 - ... expensive: (e.g., satellite with bounded energy to communicate)
 - ... noisy: (bits flipped, DVD scratched)
 - ... interactive: (complicates above further)
 - ... contextual (assumes you are running specific OS, IPvX)

Theory = Why?

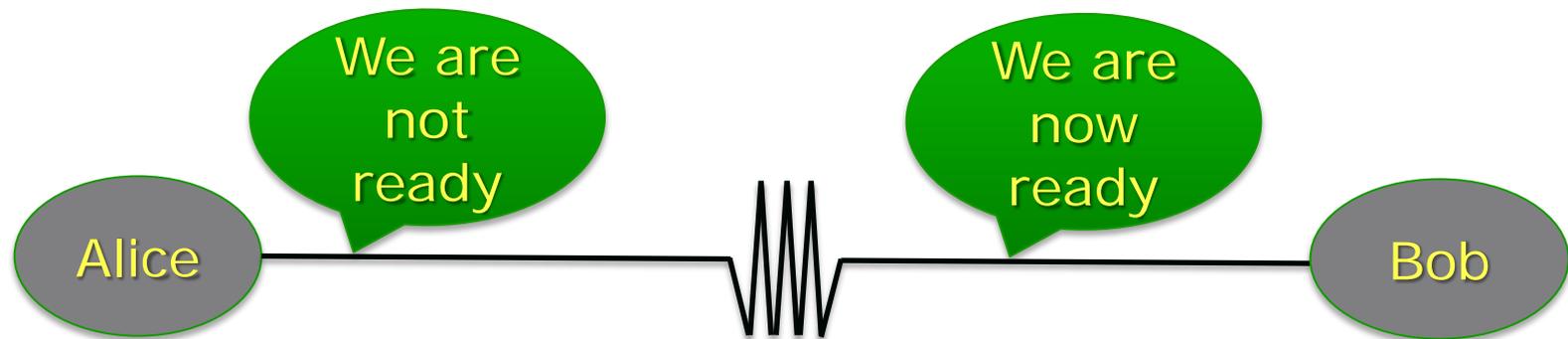
- Why build theory and not just use whatever works?
 - Ad-hoc solutions work today, but will they work tomorrow?
 - Formulating problem allows comparison of solutions!
 - And some creative solutions might be surprisingly better than naïve!
 - Better understanding of limits.
 - What can not be achieved ...

Old? New?

- Why new theories? Were old ones not good enough?
 - Quite the opposite: Old ones were too good.
 - They provided right framework and took us from ground level to "orbit"!
 - And now we can explore all of "space" ... but new possibilities leads to new challenges.

Reliable Communication?

- Problem from the 1940s: Advent of digital age.



- Communication media are always noisy
 - But digital information less tolerant to noise!

Reliability by Repetition

- Can repeat (every letter of) message to improve reliability:

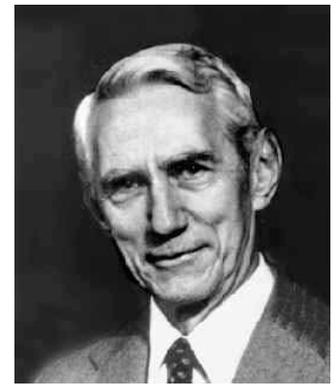
WWW EEE AAA RRR EEE NNN OOO WWW ...



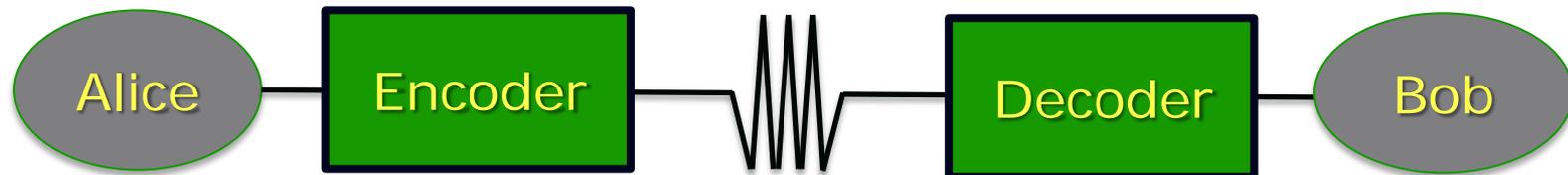
WXW EEA ARA SSR EEE NMN OOP WWW ...

- Elementary Reasoning:
 - \uparrow repetitions \Rightarrow \downarrow Prob. decoding error; but still +ve
 - \uparrow length of transmission \Rightarrow \uparrow expected # errors.
 - Combining above: Rate of repetition coding $\rightarrow 0$ as length of transmission increases.
- Belief (pre1940):
 - Rate of any scheme $\rightarrow 0$ as length $\rightarrow \infty$

Shannon's Theory [1948]



- Sender "Encodes" before transmitting
- Receiver "Decodes" after receiving



- Encoder/Decoder arbitrary functions.

$$E: \{0,1\}^k \rightarrow \{0,1\}^n$$

$$D: \{0,1\}^n \rightarrow \{0,1\}^k$$

- Rate = $\frac{k}{n}$;
- Requirement: $m = D(E(m) + \text{error})$ w. high prob.
- What are the best E, D (with highest Rate)?

Shannon's Theorem

- If every bit is flipped with probability p
 - Rate $\rightarrow 1 - H(p)$ can be achieved.

$$H(p) \triangleq p \log_2 \frac{1}{p} + (1 - p) \log_2 \frac{1}{1-p}$$

- This is best possible.

- Examples:

- $p = 0 \Rightarrow \text{Rate} = 1$

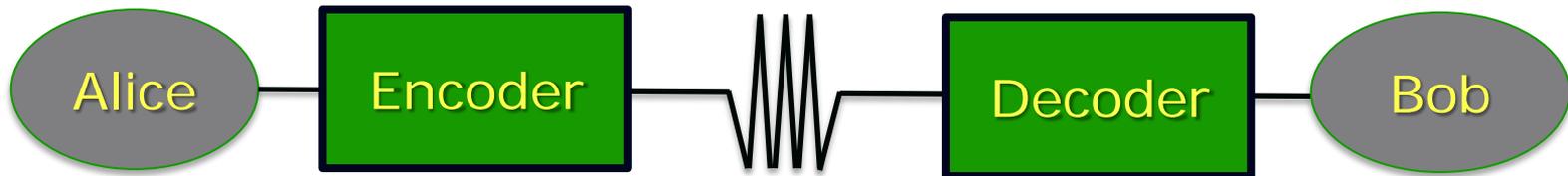
- $p = \frac{1}{2} \Rightarrow \text{Rate} = 0$

- Monotone decreasing for $p \in (0, \frac{1}{2})$

- Positive rate for $p = 0.4999$; even if $k \rightarrow \infty$

Shannon's contributions

- Far-reaching architecture:

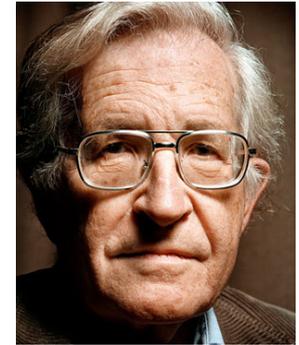


- Profound analysis:
 - First (?) use of probabilistic method.
- Deep Mathematical Discoveries:
 - Entropy, Information, Bit?

Challenges post-Shannon

- Encoding/Decoding functions not “constructive”.
 - Shannon picked E at random, D brute force.
 - Consequence:
 - D takes time $\sim 2^k$ to compute (on a computer).
 - E takes time 2^{2^k} to find!
- Algorithmic challenge:
 - Find E, D more explicitly.
 - Both should take time $\sim k, k^2, k^3 \dots$ to compute
 - Solutions: 1948-2017

Chomsky: Theory of "Language"



- Formalized syntax in languages mathematically (with caveats).
 - Initially goal was to understand inter-human communication!
 - Structure behind languages
 - Implication on acquisition.
 - Major side-effect: Use of "context-free grammars" to specify programming languages!
 - Automated parsing, compiling, interpretation!

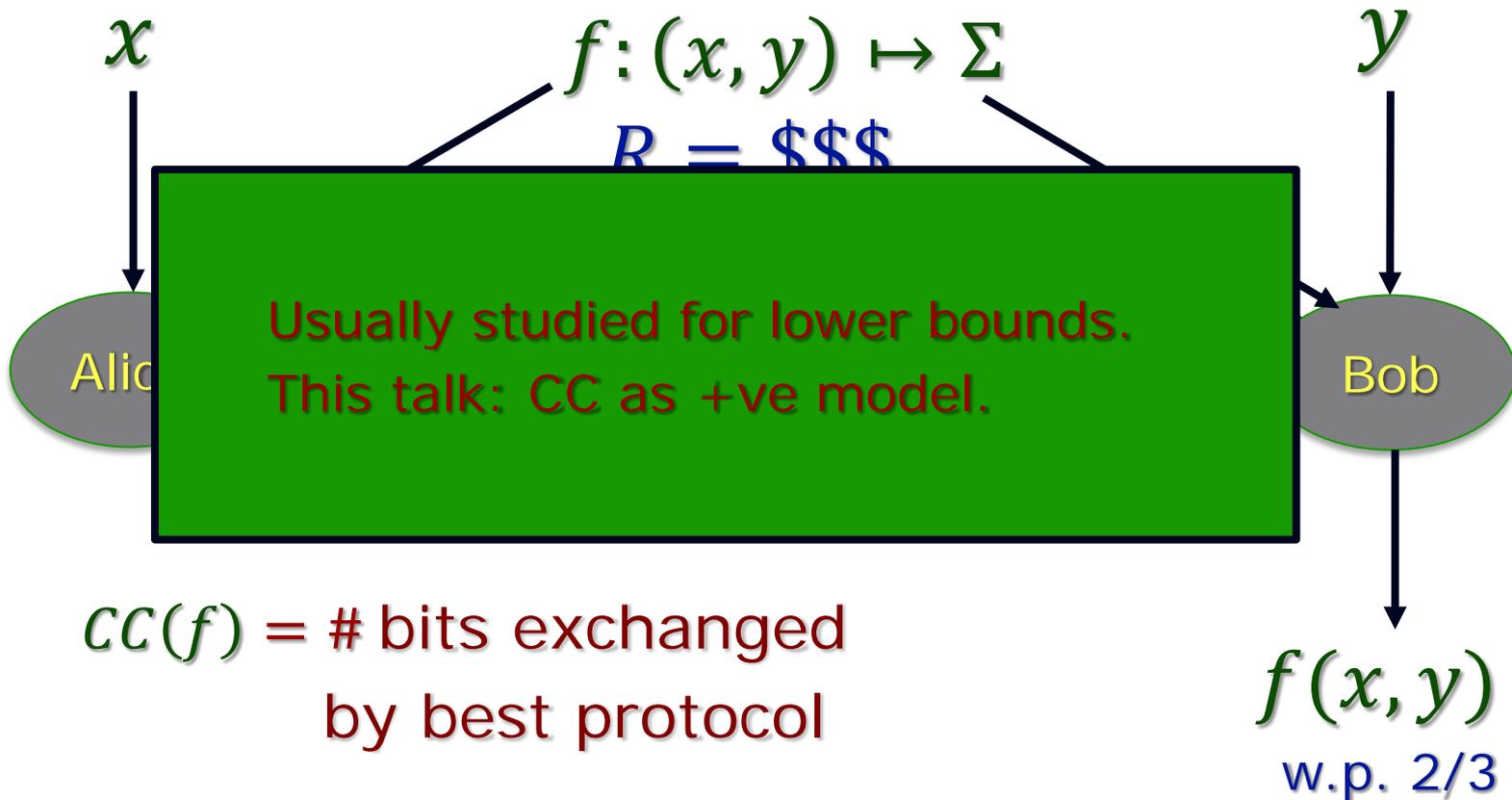
Modern Theories:

- Communication is interactive
 - E.g., "buying airline ticket online"
- Involve large inputs from either side:
 - Travel agent = vast portfolio of airlines+flights
 - Traveler = complex collection of constraints and preferences.
 - Best protocol \neq Travel agent sends brochure.
 \neq Traveller sends entire list of constraints.
- How to model? What happens if errors happen?
How well should context be shared?

Communication Complexity: Yao



The model (with shared randomness)



Some short protocols!

- Problem 1: Alice $\leftarrow x_1, \dots, x_n$; Bob $\leftarrow y_1, \dots, y_n$;
- Want to know: $(x_1 - y_1) + \dots + (x_n - y_n)$
- Solution: Alice \rightarrow Bob: $S \stackrel{\text{def}}{=} x_1 + \dots + x_n$
Bob \rightarrow Alice: $S - (y_1 + \dots + y_n)$
- Problem 2: Alice $\leftarrow x_1, \dots, x_n$; Bob $\leftarrow y_1, \dots, y_n$;
- Want to know: $(x_1 - y_1)^2 + \dots + (x_n - y_n)^2$
- Solution?
 - Deterministically: Needs n bits of communication.
 - Randomized: Say Alice+Bob $\leftarrow r_1, r_2, \dots, r_n \in \{-1, +1\}$ random.
 - Alice \rightarrow Bob: $S_1 = x_1^2 + \dots + x_n^2$; $S_2 = r_1 x_1 + \dots + r_n x_n$
 - Bob \rightarrow Alice: $T_1 = y_1 + \dots + y_n$; $T_2 = r_1 y_1 + \dots + r_n y_n$
 - Thm: $\text{Exp} [S_1 + T_1 - 2S_2 T_2] = (x_1 - y_1)^2 + \dots + (x_n - y_n)^2$

Application to Buying Air Tickets

- If we can express every flight and every user's preference as n numbers
 - (commonly done in Machine Learning)
 - Then #bits communicated $\approx 2 \cdot$ description of final itinerary.
 - Only two rounds of communication!
- Challenge: Express user preferences as numbers!
 - Not yet there ... but soon your cellphones will do it!

Interaction + Errors: Schulman



- Consider distributed update of shared document.



Typical interaction:

Server → User: Current state of document

User → Server: Update

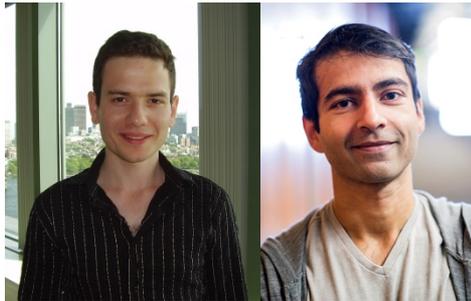
- What if there are errors in interaction?
- Error must be detected immediately?
 - Or else all future communication wasted.
- But too early detection might lead to false alarms!

Interactive Coding Schemes

- If bits are flipped with probability p what is the rate of communication?
- Limits still not precisely determined! But linear for $p \leq \frac{1}{8}$ (scales more like $1 - \sqrt{H(p)}$)



Schulman



Braverman-Rao



Kol-Raz

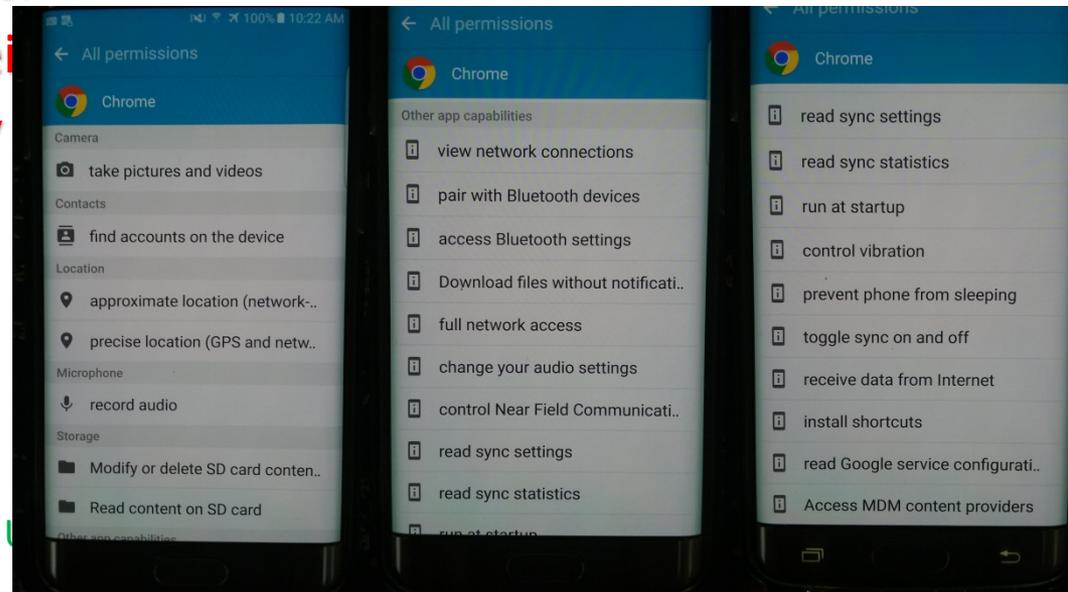


Haeupler

- Non-trivial mathematics! Some still not fully constructive
- ... surprising even given Shannon theory!

Sales Pitch + Intro

- Most of communication theory [a la Shannon, Hamming]:
 - Built around sender and receiver perfectly synchronized.
 - So large context (codes, protocols, priors) ignored.
- Most Human communication (also device-device)
 - ... does not assume perfect synchronization.
 - So context is relevant:
 - Qualitatively (reception)
 - and Quantitatively



Aside: Contextual Proofs & Uncertainty

- Mathematical proofs assume large context.
 - "By some estimates a proof that $2+2=4$ in ZFC would require about 20000 steps ... so we will use a huge set of axioms to shorten our proofs – namely, everything from high-school mathematics" [Lehman, Leighton, Meyer]
- Context shortens proofs. But context is uncertain!
 - What is "high school mathematics"
 - Is it a fixed set of axioms?
 - Or a set from which others can be derived?
 - Is the latter amenable to efficient reasoning?
 - What is efficiency with large context?

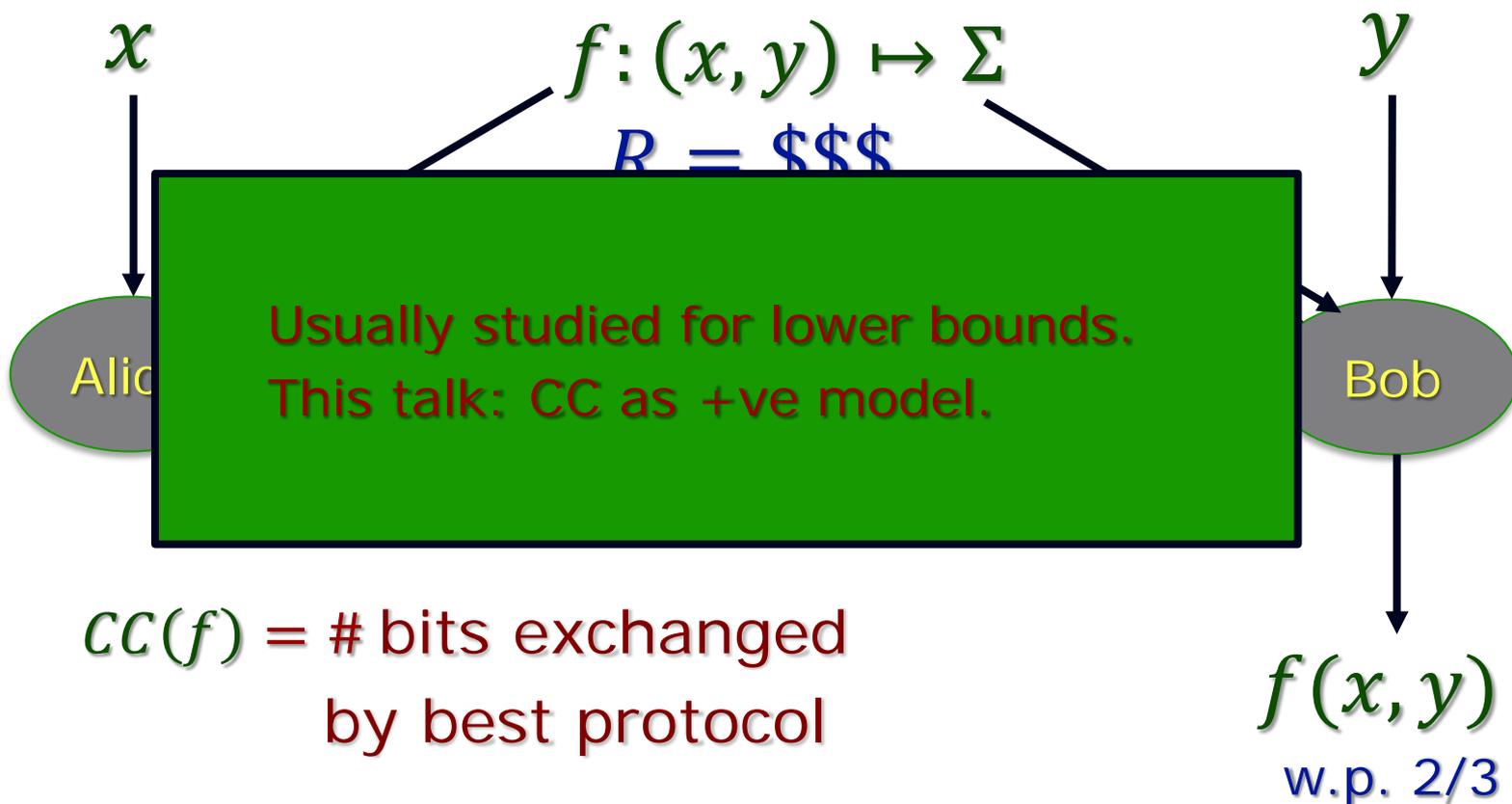
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 - So context is relevant:
 - Qualitatively (receiver takes wrong action)
 - and Quantitatively (inputs are long!!)
- Theory? What are the problems?
 - Starting point = Shannon? Yao?



Communication Complexity

The model (with shared randomness)



$CC(f)$ = # bits exchanged
by best protocol

$f(x, y)$
w.p. $2/3$

Aside: Easy CC Problems [Ghazi,Kamath,S'15]

∃ Problems with large inputs and small communication?

- Equality testing:
 - $EQ(x, y) = 1 \Leftrightarrow x = y;$
- Hamming distance:
 - $H_k(x, y) = 1 \Leftrightarrow \Delta(x, y) \leq k;$
- Small set intersection:
 - $\cap_k(x, y) = 1 \Leftrightarrow wt(x), wt(y) \leq k$
 - $CC(\cap_k) = O(k)$ [Håstad Wigderson]

Protocol:

Fix ECC $E: \{0,1\}^n \rightarrow \{0,1\}^N$

$poly(k)$ Protocol

Use common

to hash $[n] \rightarrow$

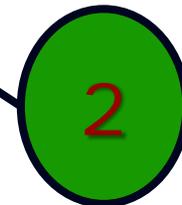
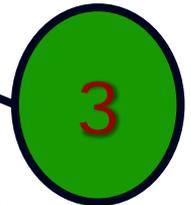
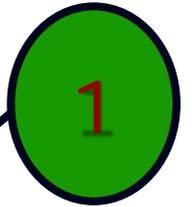
$$\begin{aligned} x &= (x_1, \dots, x_n) \\ y &= (y_1, \dots, y_n) \\ \langle x, y \rangle &\triangleq \sum_i x_i y_i \end{aligned}$$

Unstated philosophical contribution of CC a la Yao:

Communication with a focus ("only need to determine $f(x, y)$ ")
can be more effective (shorter than $|x|, H(x), H(y), I(x; y), \dots$)

Modelling Shared Context + Imperfection

- Many possibilities. Ongoing effort.
- Alice+Bob may have estimates of x and y
 - More generally: x, y close (in some sense).
- Knowledge of f – function Bob wants to compute
 - may not be exactly known to Alice!
- Shared randomness
 - Alice + Bob may not have identical copies.



1. Compression

- **Classical compression:** Alice $\leftarrow P, m \sim P$; Bob $\leftarrow P$;

- Alice \rightarrow Bob: $y = E_P(m)$; Bob $\hat{m} = D_P(y) \stackrel{?}{=} m$;

- [Shannon]: $\hat{m} = m$; w. $\mathbb{E}_{m \sim P}[|E_P(m)|] \leq H(P) + 1$
 $H(P) \stackrel{\text{def}}{=} \mathbb{E}_{m \sim P}[-\log P(m)]$

- **Uncertain compression [Juba, Kalai, Khanna, S.]**

- Alice $\leftarrow P, m \sim P$; Bob $\leftarrow Q$;

- Alice \rightarrow Bob: $y = E_P(m)$; Bob $\hat{m} = D_Q(y) \stackrel{?}{=} m$;

\rightarrow ■ P, Q Δ -close: $\forall m |\log P(m) - \log Q(m)| \leq \Delta$

- Can we get $\mathbb{E}_{m \sim P}[|E_P(m)|] \leq O(H(P) + \Delta)$?

- [JKKS] – Yes – with shared randomness.

- [CGMS] – Yes – with shared correlation.

- [Haramaty+S.] – Deterministically $O(H(P) + \log \log |\Omega|)$

Universe



Deterministic Compression: Challenge

- Say Alice and Bob have rankings of N players.
 - Rankings = bijections $\pi, \sigma : [N] \rightarrow [N]$
 - $\pi(i)$ = rank of i^{th} player in Alice's ranking.
- Further suppose they know rankings are close.
 - $\forall i \in [N]: |\pi(i) - \sigma(i)| \leq 2$.
- Bob wants to know: Is $\pi^{-1}(1) = \sigma^{-1}(1)$
- How many bits does Alice need to send (non-interactively).
 - With shared randomness – $O(1)$
 - Deterministically?
 - With Elad Haramaty: $\tilde{O}(\log^* n)$

Compression as a proxy for language

- Information theoretic study of language?
- Goal of language: Effective means of expressing information/action.
- Implicit objective of language: Make frequent messages short. Compression!
- Frequency = Known globally? Learned locally?
 - If latter – every one can't possibly agree on it;
 - Yet need to agree on language (mostly)!
 - Similar to problem of Uncertain Compression.
 - Studied formally in [Ghazi,Haramaty,Kamath,S. ITCS 17]

2. Imperfectly Shared Randomness

- Recall: Communication becomes more effective with randomness.
 - Identity, Hamming Distance, Small Set Intersection, Inner Product.
- How does performance degrade if players only share correlated variables:
 - E.g. Alice $\leftarrow r$; Bob $\leftarrow s$. $(r, s) = (r_i, t_i)_i$ i.i.d.
 $r_i, s_i \in \{-1, 1\}$; $\mathbb{E}[r_i] = \mathbb{E}[s_i] = 0$; $\mathbb{E}[r_i s_i] = \rho \in (0, 1)$;
- [CGMS '16]:
 - Comm. With perfect randomness = k
 \Rightarrow Comm. With imperfect randomness = $O_\rho(2^k)$

Imperfectly Shared Randomness

■ Easy (Complete) Problem:

- Gap Inner Product: $x, y \in \mathbb{R}^n$
- $GIP_{c,s}(x, y) = 1$ if $\langle x, y \rangle \geq \epsilon \cdot |x|_2 \cdot |y|_2$;
= 0 if $\langle x, y \rangle \leq 0$
- Decidable with $O_\rho\left(\frac{1}{\epsilon^2}\right)$ (o.w.) communication

■ Hard Problem:

- Sparse Gap Inner Product: GIP on sparse x
 - $x \in \{0,1\}^n, y \in \{-1,1\}^n; |x|_1 = 2\epsilon n$
- Classical communication = $O\left(\log\frac{1}{\epsilon}\right)$ [uses sparsity]
- No way to use sparsity with imperfect randomness.

3. Functional Uncertainty

- [Ghazi, Komargodski, Kothari, S. '16]
- Recall positive message of Yao's model:
 - Communication can be brief, if Alice knows what function $f(x, y)$ Bob wants to compute.
- What if Alice only knows f approximately?
 - Can communication still be short?

The Model

■ Recall Distributional Complexity:

- $(x, y) \sim \mu$; $\text{error}_\mu(\Pi) \stackrel{\text{def}}{=} \Pr_{x, y \sim \mu} [f(x, y) \neq \Pi(x, y)]$
- Complexity: $cc_{\mu, \epsilon}(f) \stackrel{\text{def}}{=} \min_{\Pi: \text{error}_\mu(\Pi) \leq \epsilon} \left\{ \max_{x, y} \{|\Pi(x, y)|\} \right\}$

■ Functional Uncertainty Model - I:

- Adversary picks (f, g) . Nature picks $(x, y) \sim \mu$
- Alice $\leftarrow (f, x)$; Bob $\leftarrow (g, y)$; Compute $g(x, y)$
- Promise: $\delta_\mu(f, g) \stackrel{\text{def}}{=} \Pr_\mu [f(x, y) \neq g(x, y)] \leq \delta_0$
- Goal: Compute (any) $\Pi(x, y)$ with $\delta_\mu(g, \Pi) \leq \epsilon_1$
 - (just want $\epsilon_1 \rightarrow 0$ as $\delta_0 \rightarrow 0$)
- If (f, g) part of input; this is complexity of what?

Modelling Uncertainty

- Modelled by graph \mathcal{G} of possible inputs
- Protocols know \mathcal{G} but not (f, g)

- $cc_{\mu, \epsilon}(\mathcal{G}) \stackrel{\text{def}}{=} \max_{(f, g) \in \mathcal{G}} \{cc_{\mu, \epsilon}(g)\}$

- $\delta_{\mu}(\mathcal{G}) \stackrel{\text{def}}{=} \max_{(f, g) \in \mathcal{G}} \{\delta_{\mu}(f, g)\}$

- Uncertain error:

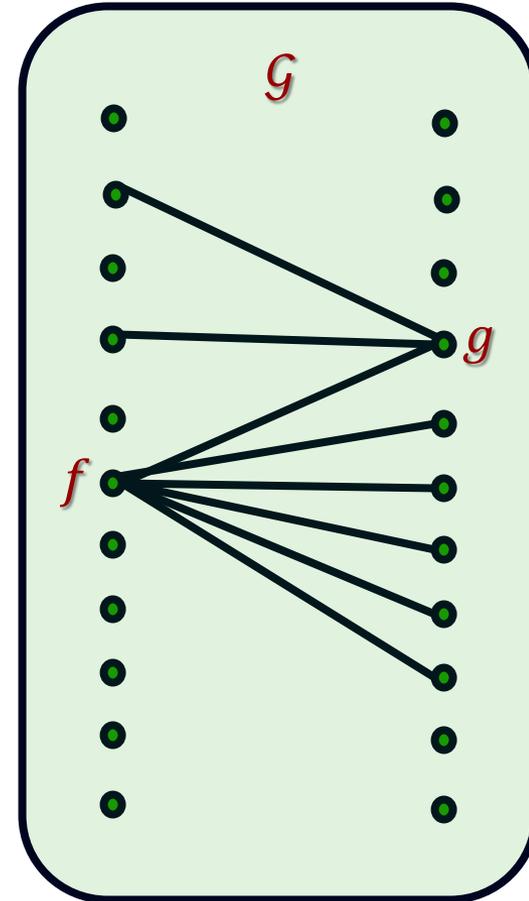
$$error_{\mu, \mathcal{G}}(\Pi) \stackrel{\text{def}}{=} \max_{(f, g) \in \mathcal{G}} \left\{ \Pr_{\mu} [g(x, y) \neq \Pi(f, g, x, y)] \right\}$$

- Uncertain complexity:

- $Ucc_{\mu, \epsilon}(\mathcal{G}) \stackrel{\text{def}}{=} \min_{\Pi: error(\Pi) \leq \epsilon} \left\{ \max_{f, g, x, y} \{|\Pi(f, g, x, y)|\} \right\}$

- Compare $cc_{\mu, \epsilon_0}(\mathcal{G})$ vs. $Ucc_{\mu, \epsilon_1}(\mathcal{G})$

want $\epsilon_1 \rightarrow 0$ as $\epsilon_0, \delta_{\mu}(\mathcal{G}) \rightarrow 0$



Main Results

- Thm 1: (-ve) $\exists \mathcal{G}, \mu$ s.t. $\delta_\mu(\mathcal{G}) = o(1)$; $cc_{\mu, o(1)}(\mathcal{G}) = 1$;
but $Ucc_{\mu, 1}(\mathcal{G}) = \Omega(\sqrt{n})$; $(n = |x| = |y|)$

- Thm 2: (+ve) $\forall \mathcal{G}$, product μ ,
 $Ucc_{\mu, \epsilon_1}^{\text{oneway}}(\mathcal{G}) = o\left(cc_{\mu, \epsilon_0}^{\text{oneway}}(\mathcal{G})\right)$

where $\epsilon_1 \rightarrow 0$ as $\epsilon_0, \delta_\mu(\mathcal{G}) \rightarrow 0$

- Thm 2': (+ve) $\forall \mathcal{G}, \mu$,
Protocols are not as continuous wrt the function being computed

$$Ucc_{\mu, \epsilon_1}^{\text{oneway}}(\mathcal{G}) = o\left(cc_{\mu, \epsilon_0}^{\text{oneway}}(\mathcal{G}) \cdot (1 + I(x; y))\right)$$

where $\epsilon_1 \rightarrow 0$ as $\epsilon_0, \delta_\mu(\mathcal{G}) \rightarrow 0$

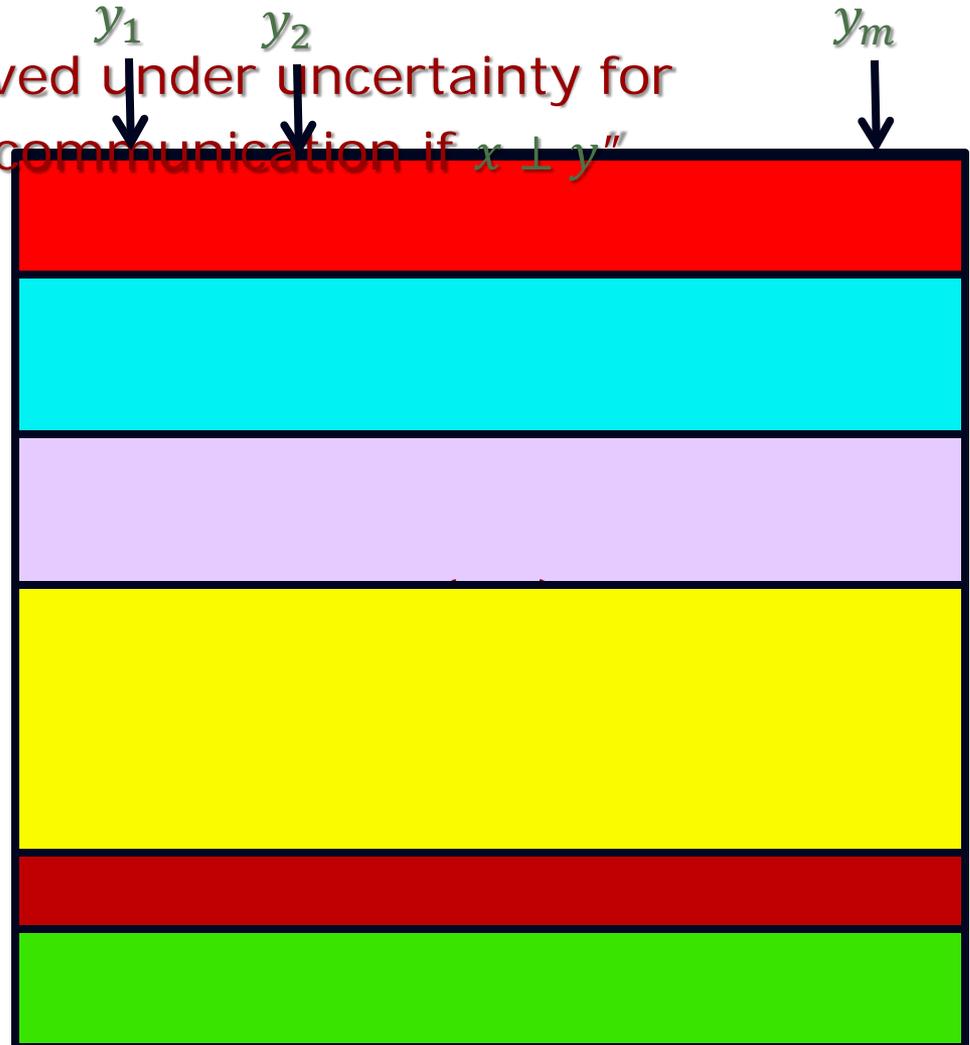
and $I(x; y) = \text{Mutual Information between } x; y$

Details of Negative Result

- $\mu: x \sim U(\{0,1\}^n); y = \text{Noisy}(x) ; \Pr[x_i \neq y_i] = 1/\sqrt{n} ;$
- $\mathcal{G} = \{(\oplus_S (x \oplus y), \oplus_T (x \oplus y)) \mid |S \oplus T| = o(\sqrt{n})\}$
 - $\oplus_S (z) = \oplus_{i \in S} z_i$
- **Certain Comm: Alice \rightarrow Bob: $\oplus_T (x)$**
- $\delta_\mu(\mathcal{G}) = \max_{S,T} \left\{ \Pr_{x,y} [\oplus_S (x \oplus y) \neq \oplus_T (x \oplus y)] \right\}$
$$= \max_{U: |U|=o(\sqrt{n})} \left\{ \Pr_{z \sim \text{Bernoulli}(\frac{1}{\sqrt{n}})} [\oplus_U (z) = 1] \right\} = o(1)$$
- **Uncertain Lower bound:**
 - Standard $c_{\mathcal{C}_{\mu,\epsilon}}(F)$ where $F((S,x);(T,y)) = \oplus_T (x \oplus y) ;$
 - Lower bound obtain by picking (S,T) randomly:
 - S uniform; T noisy copy of S

Positive result (Thm. 2)

- Consider comm. Matrix
- Protocol for g partitions matrix in 2^k blocks
- Bob wants to know which block?
- Common randomness: y_1, \dots, y_m
- Alice \rightarrow Bob: $f(x, y_1) \dots f(x, y_m)$
- Bob (whp) recognizes block and uses it.
- $m = O(k)$ suffices.



Analysis Details

1. W.p. $1 - \sqrt{\epsilon}$, $\exists j$ s.t. $\delta(g(x_j, \cdot), g(x, \cdot)) \leq \sqrt{\epsilon}$
 - Main idea: If $\Pi_g(x) = \Pi_g(x_j)$ then w.h.p. $\delta(g(x_j, \cdot), g(x, \cdot)) \leq \sqrt{\epsilon}$
2. If $j \in [K]$ s.t. $\delta(g(x_j, \cdot), g(x, \cdot)) \geq 2\sqrt{\epsilon}$ then $\Pr[j \text{ is selected}] = \exp(-m)$.
 - But Step 2. works only if $y_i \sim \mu_x$

Thm 2': Main Idea

- Now can not sample y_1, \dots, y_m independent of x
- Instead use [HJMR'07] to sample $y_i \sim \mu_x$
 - Each sample costs $I(x; y)$
- Analysis goes through ...

4. Contextual Proofs and Uncertainty?

- Scenario: Alice + Bob start with axioms A : subset of clauses on X_1, \dots, X_n
- Alice wishes to prove $A \Rightarrow C$ for some clause C
- But proof $\Pi: A \Rightarrow C$ may be long ($\sim 2^{\sqrt{n}}$)
- Context to rescue: Maybe Alice + Bob share context $D \Leftarrow A$; and contextual proof $\Pi': D \Rightarrow C$ short ($\text{poly}(n)$)
- Uncertainty: Alice's Context $D_A \neq D_B$ (Bob's context)
 - Alice writes proof $\Pi': D_A \Rightarrow C$
 - When can Bob verify Π' given D_B ?

4. Contextual Proofs and Uncertainty? -2

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 - Alice writes proof $\Pi': D_A \Rightarrow C$
 - When can Bob verify Π' given D_B ?
 - Surely if $D_A \subseteq D_B$
 - What if $D_A \setminus D_B = \{C'\}$ and $\Pi'': D_B \Rightarrow C'$ is one step long?
 - Can Bob still verify $\Pi': D_A \Rightarrow C$ in $\text{poly}(n)$ time?
 - Need feasible data structure that allows this!
 - None known to exist. Might be harder than Partial Match Retrieval ...

Summarizing

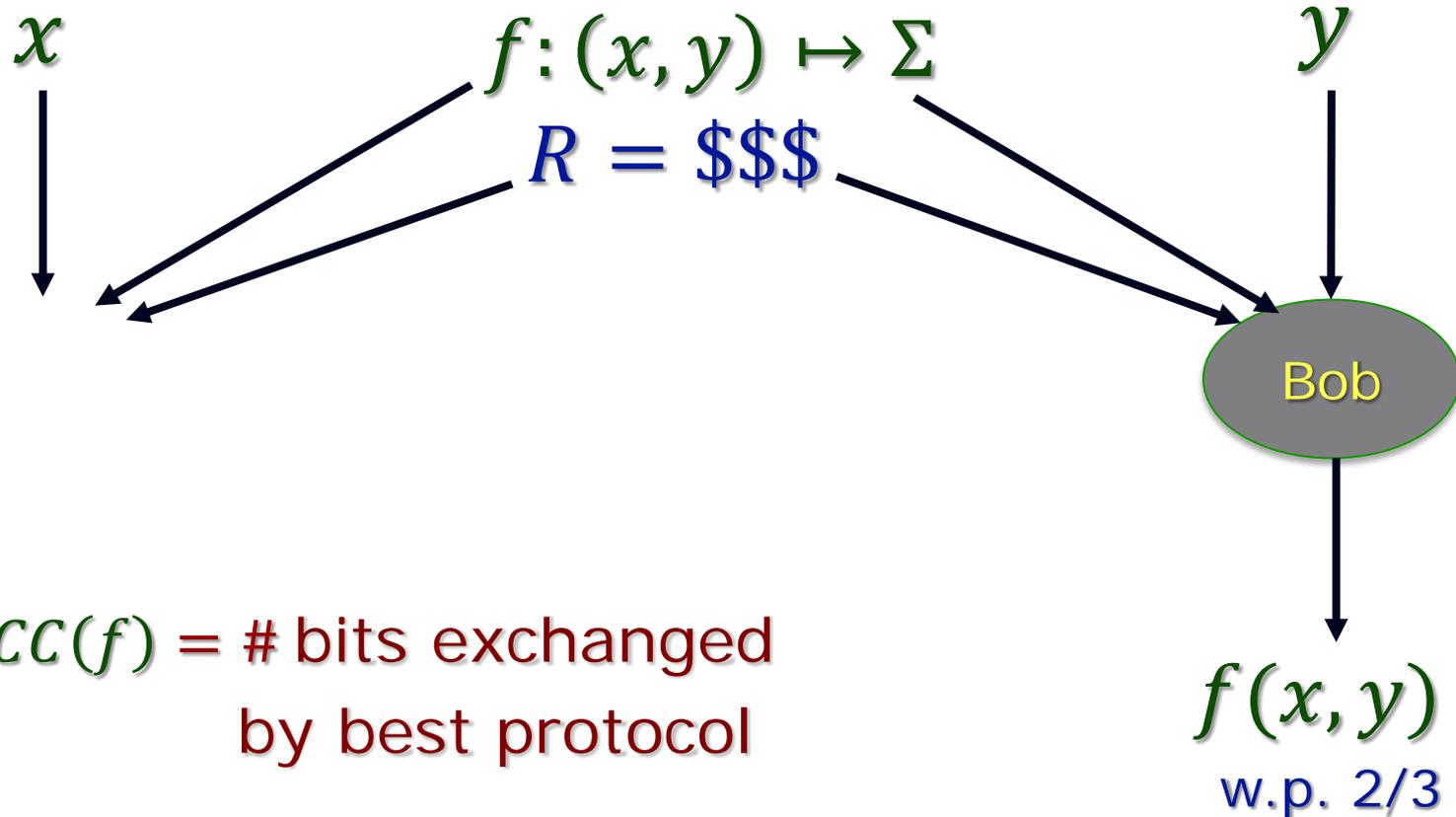
- Perturbing “common information” assumptions in Shannon/Yao theory, lead to many changes.
 - Some debilitating
 - Some not; but require careful protocol choice.
- In general: Communication protocols are not continuous functions of the common information.
- Uncertain model (\mathcal{G}) needs more exploration!
- Some open questions from our work:
 - Tighten the gap: $cc(f) \cdot I$ vs. $cc(f) + \sqrt{I}$
 - Multi-round setting? Two rounds?
 - What if randomness & function imperfectly shared? [Prelim. Results in [Ghazi+S'17]]

Contextual Communication & Uncertainty

Communication Complexity: Yao



The model (with shared randomness)



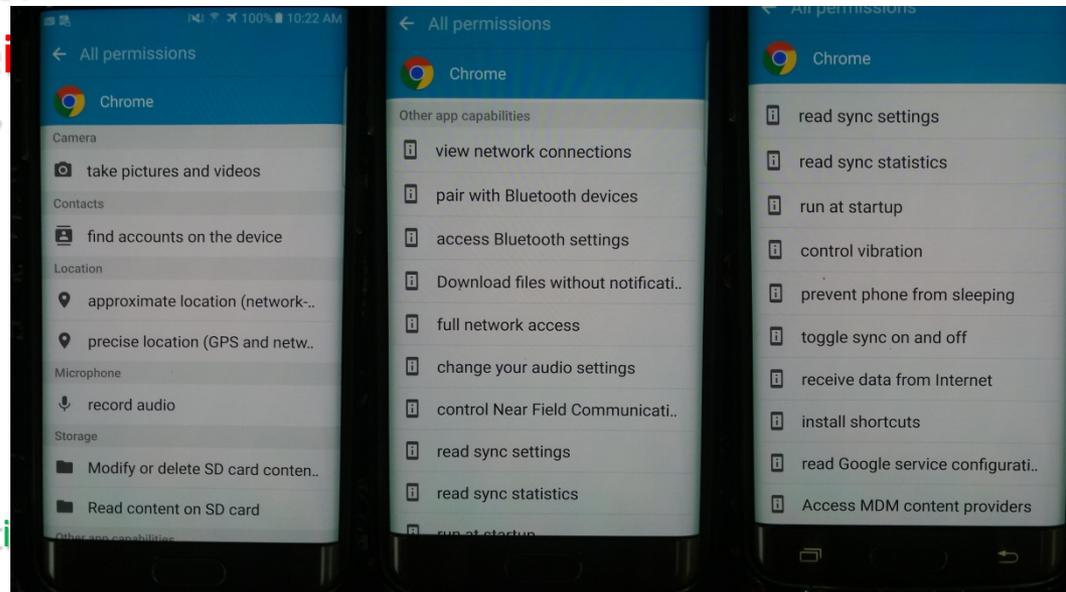
Uncertain Communication

Boole's "modest" ambition

- *"The design of the following treatise is to investigate the fundamental laws of those operations of the **mind** by which **reasoning** is performed; to give expression to them in the symbolical language of a Calculus, and upon this foundation to establish the science of **Logic** and construct its method; to make that method itself the basis of a general method for the application of the mathematical doctrine of **Probabilities**; and, finally, to collect from the various elements of truth brought to view in the course of these inquiries some probable intimations concerning the **nature and constitution** of the **human mind**."* [G.Boole, "On the laws of thought ..." p.1]

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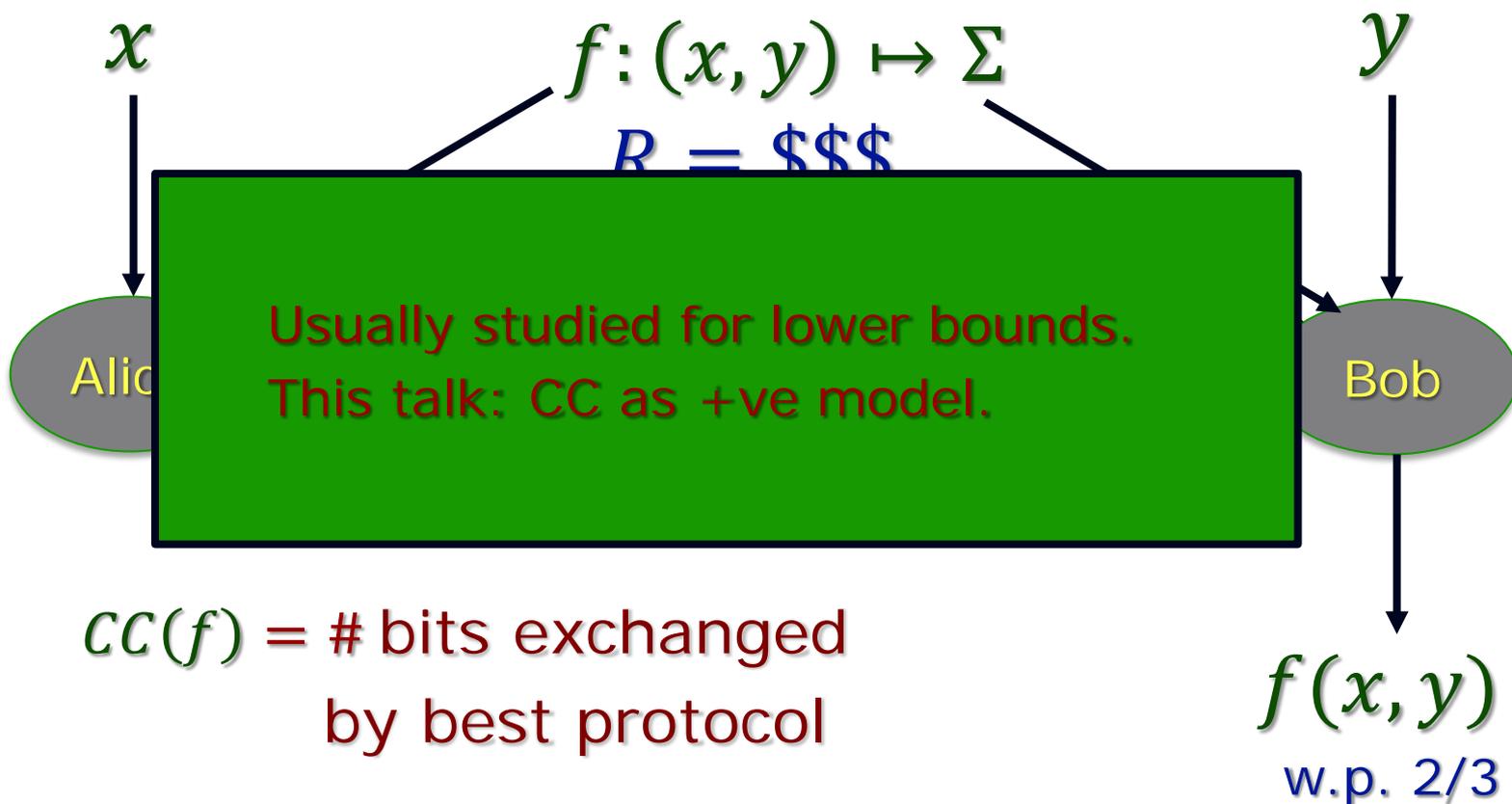
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$f(x, y)$
w.p. 2/3

Aside: Easy CC Problems [Ghazi,Kamath,S'15]

∃ Problems with large inputs and small communication?

- Equality testing:
 - $EQ(x, y) = 1 \Leftrightarrow x = y;$
- Hamming distance:
 - $H_k(x, y) = 1 \Leftrightarrow \Delta(x, y) \leq k;$
- Small set intersection:
 - $\cap_k(x, y) = 1 \Leftrightarrow wt(x), wt(y) \leq k$
 - $CC(\cap_k) = O(k)$ [Håstad Wigderson]

Protocol:

Fix ECC $E: \{0,1\}^n \rightarrow \{0,1\}^N$

$poly(k)$ Protocol

Use common

to hash $[n] \rightarrow$

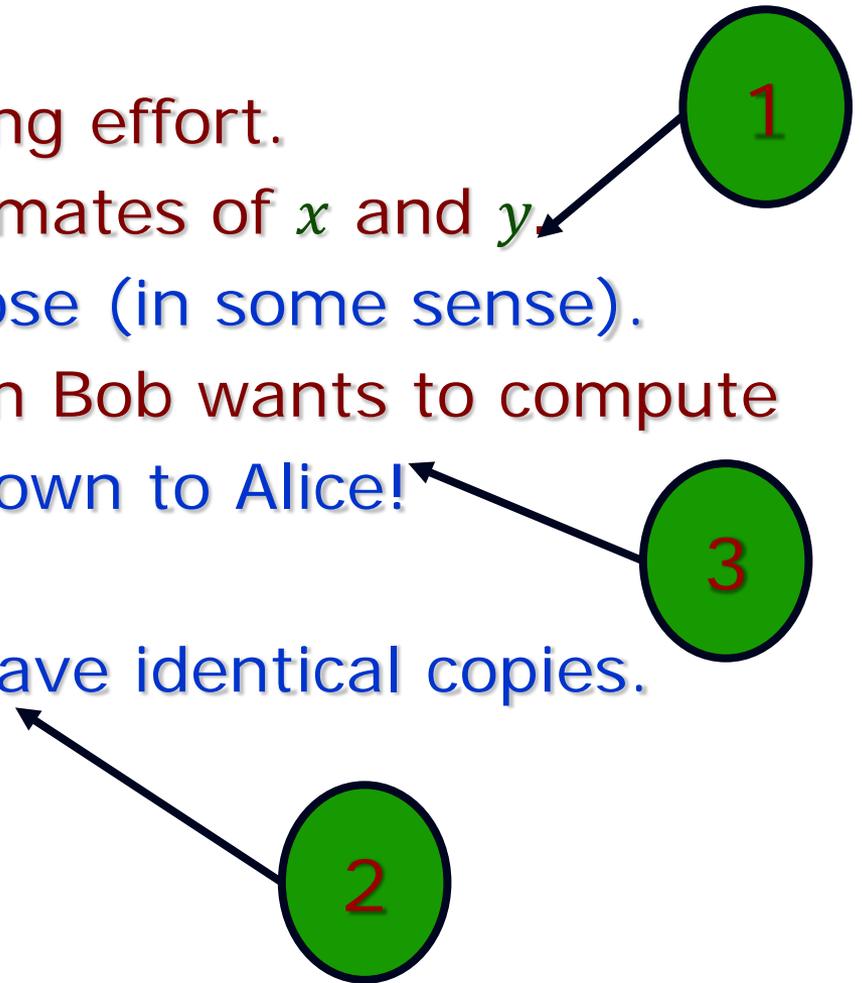
$$\begin{aligned}
 x &= (x_1, \dots, x_n) \\
 y &= (y_1, \dots, y_n) \\
 \langle x, y \rangle &\triangleq \sum_i x_i y_i
 \end{aligned}$$

Unstated philosophical contribution of CC a la Yao:

Communication with a focus ("only need to determine $f(x, y)$ ")
 can be more effective (shorter than $|x|, H(x), H(y), I(x; y), \dots$)

Modelling Shared Context + Imperfection

- Many possibilities. Ongoing effort.
- Alice+Bob may have estimates of x and y
 - More generally: x, y close (in some sense).
- Knowledge of f – function Bob wants to compute
 - may not be exactly known to Alice!
- Shared randomness
 - Alice + Bob may not have identical copies.



1. Compression

- Classical compression: Alice $\leftarrow P, m \sim P$; Bob $\leftarrow P$;

- Alice \rightarrow Bob: $y = E_P(m)$; Bob $\hat{m} = D_P(y) \stackrel{?}{=} m$;

- [Shannon]: $\hat{m} = m$; w. $\mathbb{E}_{m \sim P}[|E_P(m)|] \leq H(P) + 1$
 $H(P) \stackrel{\text{def}}{=} \mathbb{E}_{m \sim P}[-\log P(m)]$

- Uncertain compression [Juba, Kalai, Khanna, S.]

- Alice $\leftarrow P, m \sim P$; Bob $\leftarrow Q$;

- Alice \rightarrow Bob: $y = E_P(m)$; Bob $\hat{m} = D_Q(y) \stackrel{?}{=} m$;

→

- P, Q Δ -close: $\forall m |\log P(m) - \log Q(m)| \leq \Delta$

- Can we get $\mathbb{E}_{m \sim P}[|E_P(m)|] \leq O(H(P) + \Delta)$?

- [JKKS] – Yes – with shared randomness.

- [CGMS] – Yes – with shared correlation.

- [Haramaty+S.] – Deterministically $O(H(P) + \log \log |\Omega|)$

Universe



Deterministic Compression: Challenge

- Say Alice and Bob have rankings of N players.
 - Rankings = bijections $\pi, \sigma : [N] \rightarrow [N]$
 - $\pi(i)$ = rank of i^{th} player in Alice's ranking.
- Further suppose they know rankings are close.
 - $\forall i \in [N]: |\pi(i) - \sigma(i)| \leq 2$.
- Bob wants to know: Is $\pi^{-1}(1) = \sigma^{-1}(1)$
- How many bits does Alice need to send (non-interactively).
 - With shared randomness – $O(1)$
 - Deterministically?
 - With Elad Haramaty: $\tilde{O}(\log^* n)$

Compression as a proxy for language

- Information theoretic study of language?
- Goal of language: Effective means of expressing information/action.
- Implicit objective of language: Make frequent messages short. Compression!
- Frequency = Known globally? Learned locally?
 - If latter – every one can't possibly agree on it;
 - Yet need to agree on language (mostly)!
 - Similar to problem of Uncertain Compression.
 - Studied formally in [Ghazi,Haramaty,Kamath,S. ITCS 17]

2. Imperfectly Shared Randomness

- Recall: Communication becomes more effective with randomness.
 - Identity, Hamming Distance, Small Set Intersection, Inner Product.
- How does performance degrade if players only share correlated variables:
 - E.g. Alice $\leftarrow r$; Bob $\leftarrow s$. $(r, s) = (r_i, t_i)_i$ i.i.d.
 $r_i, s_i \in \{-1, 1\}$; $\mathbb{E}[r_i] = \mathbb{E}[s_i] = 0$; $\mathbb{E}[r_i s_i] = \rho \in (0, 1)$;
- [CGMS '16]:
 - Comm. With perfect randomness = k
 \Rightarrow Comm. With imperfect randomness = $O_\rho(2^k)$

Imperfectly Shared Randomness

- **Easy (Complete) Problem:**
 - Gap Inner Product: $x, y \in \mathbb{R}^n$
 - $GIP_{c,s}(x, y) = 1$ if $\langle x, y \rangle \geq \epsilon \cdot |x|_2 \cdot |y|_2$;
= 0 if $\langle x, y \rangle \leq 0$
 - Decidable with $O_\rho\left(\frac{1}{\epsilon^2}\right)$ (o.w.) communication
- **Hard Problem:**
 - Sparse Gap Inner Product: GIP on sparse x
 - $x \in \{0,1\}^n, y \in \{-1,1\}^n; |x|_1 = 2\epsilon n$
 - Classical communication = $O\left(\log\frac{1}{\epsilon}\right)$ [uses sparsity]
 - No way to use sparsity with imperfect randomness.

3. Functional Uncertainty

- [Ghazi, Komargodski, Kothari, S. '16]
- Recall positive message of Yao's model:
 - Communication can be brief, if Alice knows what function $f(x, y)$ Bob wants to compute.
- What if Alice only knows f approximately?
 - Can communication still be short?

The Model

■ Recall Distributional Complexity:

- $(x, y) \sim \mu$; $\text{error}_\mu(\Pi) \stackrel{\text{def}}{=} \Pr_{x, y \sim \mu} [f(x, y) \neq \Pi(x, y)]$
- Complexity: $cc_{\mu, \epsilon}(f) \stackrel{\text{def}}{=} \min_{\Pi: \text{error}_\mu(\Pi) \leq \epsilon} \left\{ \max_{x, y} \{|\Pi(x, y)|\} \right\}$

■ Functional Uncertainty Model - I:

- Adversary picks (f, g) . Nature picks $(x, y) \sim \mu$
- Alice $\leftarrow (f, x)$; Bob $\leftarrow (g, y)$; Compute $g(x, y)$
- Promise: $\delta_\mu(f, g) \stackrel{\text{def}}{=} \Pr_{\mu} [f(x, y) \neq g(x, y)] \leq \delta_0$
- Goal: Compute (any) $\Pi(x, y)$ with $\delta_\mu(g, \Pi) \leq \epsilon_1$
 - (just want $\epsilon_1 \rightarrow 0$ as $\delta_0 \rightarrow 0$)
- If (f, g) part of input; this is complexity of what?

Modelling Uncertainty

- Modelled by graph \mathcal{G} of possible inputs
- Protocols know \mathcal{G} but not (f, g)

- $cc_{\mu, \epsilon}(\mathcal{G}) \stackrel{\text{def}}{=} \max_{(f, g) \in \mathcal{G}} \{cc_{\mu, \epsilon}(g)\}$

- $\delta_{\mu}(\mathcal{G}) \stackrel{\text{def}}{=} \max_{(f, g) \in \mathcal{G}} \{\delta_{\mu}(f, g)\}$

- Uncertain error:

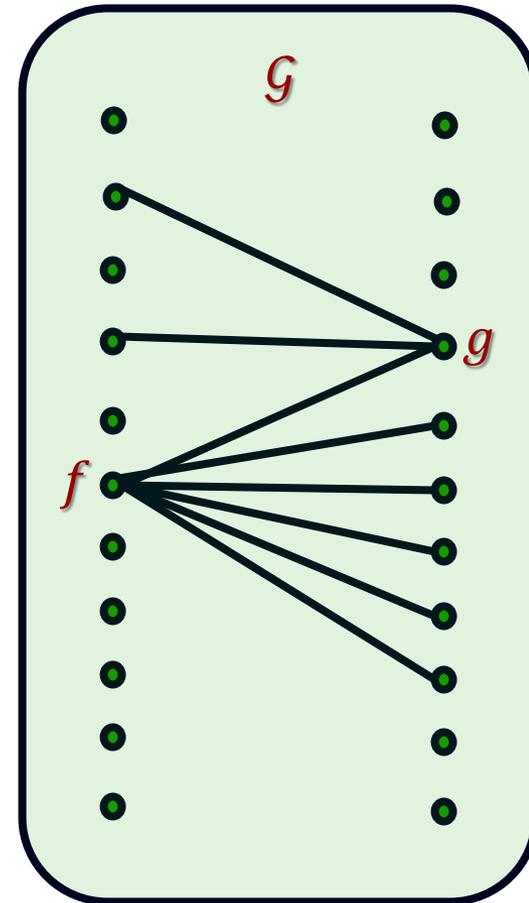
$$error_{\mu, \mathcal{G}}(\Pi) \stackrel{\text{def}}{=} \max_{(f, g) \in \mathcal{G}} \left\{ \Pr_{\mu} [g(x, y) \neq \Pi(f, g, x, y)] \right\}$$

- Uncertain complexity:

- $Ucc_{\mu, \epsilon}(\mathcal{G}) \stackrel{\text{def}}{=} \min_{\Pi: error(\Pi) \leq \epsilon} \left\{ \max_{f, g, x, y} \{|\Pi(f, g, x, y)|\} \right\}$

- Compare $cc_{\mu, \epsilon_0}(\mathcal{G})$ vs. $Ucc_{\mu, \epsilon_1}(\mathcal{G})$

want $\epsilon_1 \rightarrow 0$ as $\epsilon_0, \delta_{\mu}(\mathcal{G}) \rightarrow 0$



Main Results

- Thm 1: (-ve) $\exists \mathcal{G}, \mu$ s.t. $\delta_\mu(\mathcal{G}) = o(1)$; $cc_{\mu, o(1)}(\mathcal{G}) = 1$;
but $Ucc_{\mu, 1}(\mathcal{G}) = \Omega(\sqrt{n})$; $(n = |x| = |y|)$

- Thm 2: (+ve) $\forall \mathcal{G}$, product μ ,
 $Ucc_{\mu, \epsilon_1}^{\text{oneway}}(\mathcal{G}) = o\left(cc_{\mu, \epsilon_0}^{\text{oneway}}(\mathcal{G})\right)$

where $\epsilon_1 \rightarrow 0$ as $\epsilon_0, \delta_\mu(\mathcal{G}) \rightarrow 0$

- Thm 2': (+ve) $\forall \mathcal{G}, \mu$,
Protocols are not as continuous wrt the function being computed

$$Ucc_{\mu, \epsilon_1}^{\text{oneway}}(\mathcal{G}) = o\left(cc_{\mu, \epsilon_0}^{\text{oneway}}(\mathcal{G}) \cdot (1 + I(x; y))\right)$$

where $\epsilon_1 \rightarrow 0$ as $\epsilon_0, \delta_\mu(\mathcal{G}) \rightarrow 0$

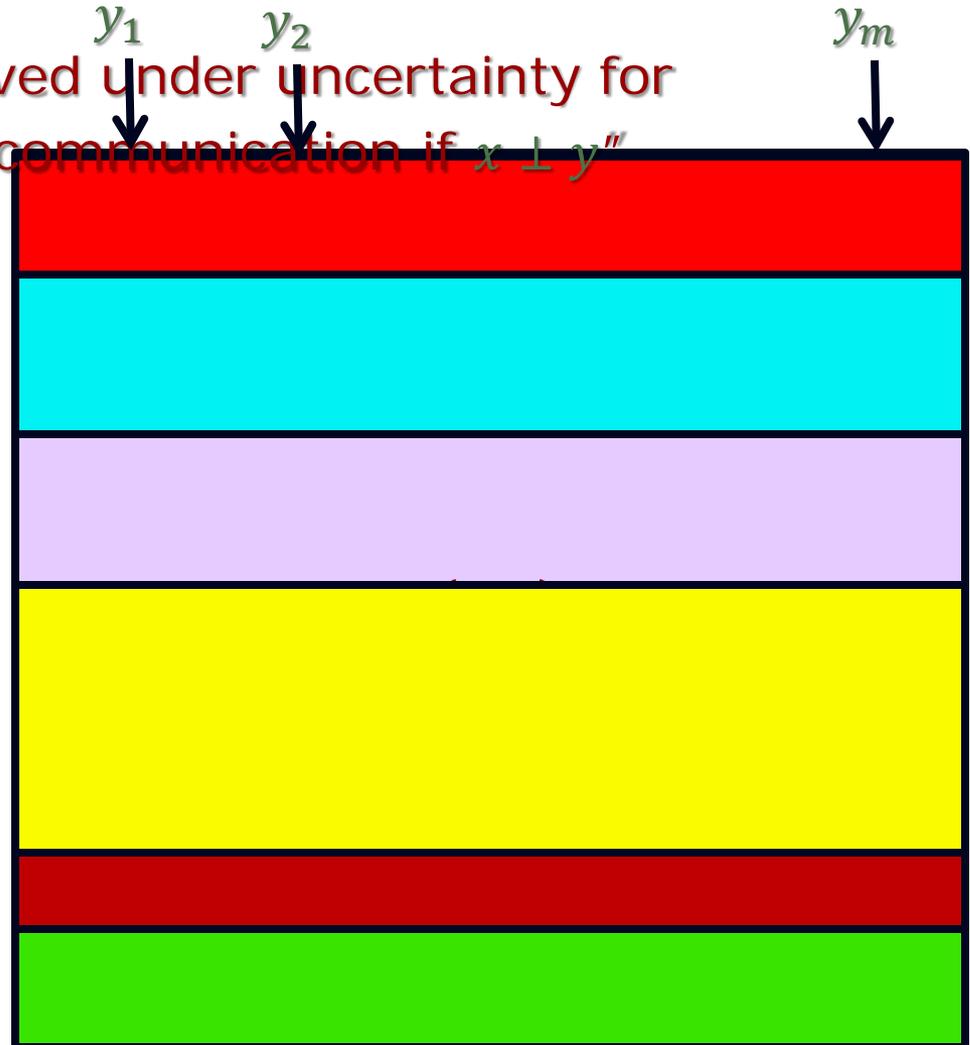
and $I(x; y) = \text{Mutual Information between } x; y$

Details of Negative Result

- $\mu: x \sim U(\{0,1\}^n); y = \text{Noisy}(x) ; \Pr[x_i \neq y_i] = 1/\sqrt{n} ;$
- $\mathcal{G} = \{(\oplus_S (x \oplus y), \oplus_T (x \oplus y)) \mid |S \oplus T| = o(\sqrt{n})\}$
 - $\oplus_S (z) = \oplus_{i \in S} z_i$
- **Certain Comm: Alice \rightarrow Bob: $\oplus_T (x)$**
- $\delta_\mu(\mathcal{G}) = \max_{S,T} \left\{ \Pr_{x,y} [\oplus_S (x \oplus y) \neq \oplus_T (x \oplus y)] \right\}$
 $= \max_{U: |U|=o(\sqrt{n})} \left\{ \Pr_{z \sim \text{Bernoulli}(\frac{1}{\sqrt{n}})} [\oplus_U (z) = 1] \right\} = o(1)$
- **Uncertain Lower bound:**
 - Standard $c_{\mathcal{C}_{\mu,\epsilon}}(F)$ where $F((S,x);(T,y)) = \oplus_T (x \oplus y) ;$
 - Lower bound obtain by picking (S,T) randomly:
 - S uniform; T noisy copy of S

Positive result (Thm. 2)

- Consider comm. Matrix
- Protocol for g partitions matrix in 2^k blocks
- Bob wants to know which block?
- Common randomness: y_1, \dots, y_m
- Alice \rightarrow Bob: $f(x, y_1) \dots f(x, y_m)$
- Bob (whp) recognizes block and uses it.
- $m = O(k)$ suffices.



Analysis Details

1. W.p. $1 - \sqrt{\epsilon}$, $\exists j$ s.t. $\delta(g(x_j, \cdot), g(x, \cdot)) \leq \sqrt{\epsilon}$
 - Main idea: If $\Pi_g(x) = \Pi_g(x_j)$ then w.h.p. $\delta(g(x_j, \cdot), g(x, \cdot)) \leq \sqrt{\epsilon}$
2. If $j \in [K]$ s.t. $\delta(g(x_j, \cdot), g(x, \cdot)) \geq 2\sqrt{\epsilon}$ then $\Pr[j \text{ is selected}] = \exp(-m)$.
 - But Step 2. works only if $y_i \sim \mu_x$

Thm 2': Main Idea

- Now can not sample y_1, \dots, y_m independent of x
- Instead use [HJMR'07] to sample $y_i \sim \mu_x$
 - Each sample costs $I(x; y)$
- Analysis goes through ...

4. Contextual Proofs and Uncertainty?

- Scenario: Alice + Bob start with axioms A : subset of clauses on X_1, \dots, X_n
- Alice wishes to prove $A \Rightarrow C$ for some clause C
- But proof $\Pi: A \Rightarrow C$ may be long ($\sim 2^{\sqrt{n}}$)
- Context to rescue: Maybe Alice + Bob share context $D \Leftarrow A$; and contextual proof $\Pi': D \Rightarrow C$ short ($\text{poly}(n)$)
- Uncertainty: Alice's Context $D_A \neq D_B$ (Bob's context)
 - Alice writes proof $\Pi': D_A \Rightarrow C$
 - When can Bob verify Π' given D_B ?

4. Contextual Proofs and Uncertainty? -2

- Scenario: Alice + Bob start with axioms A : subset of clauses on X_1, \dots, X_n
- Alice wishes to prove $A \Rightarrow C$ for some clause C
 - Alice writes proof $\Pi': D_A \Rightarrow C$
 - When can Bob verify Π' given D_B ?
 - Surely if $D_A \subseteq D_B$
 - What if $D_A \setminus D_B = \{C'\}$ and $\Pi'': D_B \Rightarrow C'$ is one step long?
 - Can Bob still verify $\Pi': D_A \Rightarrow C$ in $\text{poly}(n)$ time?
 - Need feasible data structure that allows this!
 - None known to exist. Might be harder than Partial Match Retrieval ...

Summarizing

- Perturbing “common information” assumptions in Shannon/Yao theory, lead to many changes.
 - Some debilitating
 - Some not; but require careful protocol choice.
- In general: Communication protocols are not continuous functions of the common information.
- Uncertain model (\mathcal{G}) needs more exploration!
- Some open questions from our work:
 - Tighten the gap: $cc(f) \cdot I$ vs. $cc(f) + \sqrt{I}$
 - Multi-round setting? Two rounds?
 - What if randomness & function imperfectly shared? [Prelim. Results in [Ghazi+S'17]]

Thank You!